Random Matrix Theory for Modern Machine Learning: New Intuitions, Improved Methods, and Beyond: Part 1 Short Course @ Institut de Mathématiques de Toulouse, France

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RMT4ML

- Monday, July 1st (today): Motivation and Mathematical Background (concentration, resolvent-based approach to eigenspectral analysis, etc.)
- Tuesday, July 2nd (afternoon): Four Ways to Characterize Sample Covariance Matrices and Some More Random Matrix Models (Wigner semicircle law, generalized sample covariance model, and separable covariance model)
- Wednesday, July 3rd: Linear Master Theorem (information-plus-noise and additive spiked models) and RMT for Linear Machine Learning (Low-rank approximation, classification, and linear least squares)
- Thursday, July 4th: Linearization of Nonlinear Models (Taylor expansion and Orthogonal Polynomial) and Nonlinear ML models via linearization: Kernel Methods in the Proportional Regime

Outline

Introduction and Motivation

- Sample covariance matrix
- RMT for machine learning: kernel spectral clustering

2 Mathematical Background

- From random scalars to random vectors, LLN, and CLT
- A quick recap on linear algebra
- A unified spectral analysis approach via the resolvent

Motivation: understanding large-dimensional machine learning



- **Big Data era**: exploit large *n*, *p*, *N*
- counterintuitive phenomena different from classical asymptotics statistics
- complete change of understanding of many methods in statistics, machine learning, signal processing, and wireless communications
- Random Matrix Theory (RMT) provides the tools!

Sample covariance matrix in the large *n*, *p* regime

- ▶ **Problem**: estimate covariance $\mathbf{C} \in \mathbb{R}^{p \times p}$ from *n* data samples $\mathbf{x}_1, \ldots, \mathbf{x}_n$ with $\mathbf{x}_i \sim \mathcal{N}(\mathbf{0}, \mathbf{C})$,
- Maximum likelihood sample covariance matrix with entry-wise convergence

$$\hat{\mathbf{C}} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}_i \mathbf{x}_i^{\mathsf{T}} \in \mathbb{R}^{p \times p}, \quad [\hat{\mathbf{C}}]_{ij} \to [\mathbf{C}]_{ij}$$

almost surely as $n \to \infty$: optimal for $n \gg p$ (or, for p "small").

In the regime $n \sim p$, conventional wisdom breaks down: for $\mathbf{C} = \mathbf{I}_p$ with n < p, $\hat{\mathbf{C}}$ has at least p - n zero eigenvalues:

 $\|\hat{\mathbf{C}} - \mathbf{C}\| \not\rightarrow 0, \quad n, p \rightarrow \infty \Rightarrow \text{ eigenvalue mismatch and not consistent!}$

• due to loss of matrix norm "equivalence": $\|\mathbf{A}\|_{\max} \le \|\mathbf{A}\| \le p \|\mathbf{A}\|_{\max}$ for $\mathbf{A} \in \mathbb{R}^{p \times p}$ and $\|\mathbf{A}\|_{\max} \equiv \max_{ij} |\mathbf{A}_{ij}|$.

When is one in the random matrix regime? Almost always!

What about n = 100p? For $\mathbf{C} = \mathbf{I}_p$, as $n, p \to \infty$ with $p/n \to c \in (0, \infty)$: MP law

$$\mu(dx) = (1 - c^{-1})^+ \delta(x) + \frac{1}{2\pi cx} \sqrt{(x - E_-)^+ (E_+ - x)^+} dx$$

where $E_{-} = (1 - \sqrt{c})^2$, $E_{+} = (1 + \sqrt{c})^2$ and $(x)^+ \equiv \max(x, 0)$. Close match!



Figure: Eigenvalue distribution of $\hat{\mathbf{C}}$ versus Marčenko-Pastur law, p = 500, n = 50000.

- eigenvalues span on $[E_- = (1 \sqrt{c})^2, E_+ = (1 + \sqrt{c})^2]$.
- for n = 100p, on a range of $\pm 2\sqrt{c} = \pm 0.2$ around the population eigenvalue 1.

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- large-*n* intuition, and many existing popular methods in biology, finance, signal processing, telecommunication, and machine learning, must **fail** even with n = 100p!
- **RMT** as a flexible and powerful tool to **understand** and **recreate** these methods
- ▶ in essence: large-scale system with increasing complexity in need of low complexity analysis
- as an motivating example, how RMT can be applied to assess kernel spectral clustering in machine learning

"Curse of dimensionality": loss of relevance of Euclidean distance

▶ Binary Gaussian mixture classification $\mathbf{x} \in \mathbb{R}^p$:

$$C_1$$
: $\mathbf{x} \sim \mathcal{N}(\boldsymbol{\mu}_1, \mathbf{C}_1)$, versus C_2 : $\mathbf{x} \sim \mathcal{N}(\boldsymbol{\mu}_2, \mathbf{C}_2)$;

Neyman-Pearson test: classification is possible only when

$$\|\mu_1 - \mu_2\| \ge C_{\mu}$$
, or $\|\mathbf{C}_1 - \mathbf{C}_2\| \ge C_{\mathbf{C}} \cdot p^{-1/2}$

for some constants C_{μ} , $C_{\mathbf{C}} > 0$ [CLM18].

▶ In this non-trivial setting, for $\mathbf{x}_i \in C_a$, $\mathbf{x}_j \in C_b$:

$$\max_{1 \le i \ne j \le n} \left\{ \left| \frac{1}{p} \| \mathbf{x}_i - \mathbf{x}_j \|^2 - \frac{2}{p} \operatorname{tr} \mathbf{C}^{\circ} \right| \right\} \xrightarrow{a.s.} 0$$

as $n, p \to \infty$ (i.e., $n \sim p$), for $\mathbf{C}^{\circ} \equiv \frac{1}{2}(\mathbf{C}_1 + \mathbf{C}_2)$, regardless of the classes $\mathcal{C}_a, \mathcal{C}_b$!

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¹Romain Couillet, Zhenyu Liao, and Xiaoyi Mai. "Classification asymptotics in the random matrix regime". In: 2018 26th European Signal Processing Conference (EUSIPCO). IEEE. 2018, pp. 1875–1879

Loss of relevance of Euclidean distance: visual representation



Figure: Visual representation of classification in (left) small and (right) large dimensions.

⇒ Direct consequence to various distance-based machine learning methods (e.g., kernel spectral clustering)!

Reminder on kernel spectral clustering

Two-step classification of *n* data points with distance kernel $\mathbf{K} \equiv \{f(||\mathbf{x}_i - \mathbf{x}_j||^2/p)\}_{i,i=1}^n$:



Reminder on kernel spectral clustering





\Downarrow *K*-dimensional representation \Downarrow



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Cluster Gaussian data $\mathbf{x}_1, \ldots, \mathbf{x}_n \in \mathbf{R}^p$ into C_1 or C_2 , with second top eigenvectors \mathbf{v}_2 of heat kernel $\mathbf{K}_{ij} = \exp(-\|\mathbf{x}_i - \mathbf{x}_j\|^2/2p)$, small and large dimensional data.

(a)
$$p = 5, n = 500$$
 (b) $p = 250, n = 500$



Kernel matrices for large dimensional real-world data



• "local" linearization of **nonlinear** kernel matrices in large dimensions, e.g., Gaussian kernel matrix $\mathbf{K}_{ij} = \exp(-\|\mathbf{x}_i - \mathbf{x}_j\|^2/2p)$ with $\mathbf{C}_1 = \mathbf{C}_2 = \mathbf{I}_p$ (e.g., $C_1 : \mathbf{x}_i = \mu_1 + \mathbf{z}_i$ versus $C_2 : \mathbf{x}_j = \mu_2 + \mathbf{z}_j$) so that

$$\|\mathbf{x}_{i} - \mathbf{x}_{j}\|^{2} / p \xrightarrow{a.s.}{2}, \text{ and } \mathbf{K} = \exp\left(-\frac{2}{2}\right) \left(\mathbf{1}_{n}\mathbf{1}_{n}^{\mathsf{T}} + \frac{1}{p}\mathbf{Z}^{\mathsf{T}}\mathbf{Z}\right) + g(\|\boldsymbol{\mu}_{1} - \boldsymbol{\mu}_{2}\|)\frac{1}{p}\mathbf{j}\mathbf{j}^{\mathsf{T}} + * + o_{\|\cdot\|}(1)$$

with Gaussian $\mathbf{Z} = [\mathbf{z}_1, \dots, \mathbf{z}_n] \in \mathbb{R}^{p \times n}$ and class-information $\mathbf{j} = [\mathbf{1}_{n/2}; -\mathbf{1}_{n/2}]$,

▶ accumulated effect of small "hidden" statistical information ($\|\mu_1 - \mu_2\|$ in this case)

A RMT viewpoint of large kernel matrices

Therefore

entry-wise:

$$\mathbf{K}_{ij} = \exp(-1)\left(1 + \underbrace{\frac{1}{p}\mathbf{z}_{i}^{\mathsf{T}}\mathbf{z}_{j}}_{O(p^{-1/2})}\right) \pm \underbrace{\frac{1}{p}g(\|\boldsymbol{\mu}_{1} - \boldsymbol{\mu}_{2}\|)}_{O(p^{-1})} + *, \text{ so that } \frac{1}{p}g(\|\boldsymbol{\mu}_{1} - \boldsymbol{\mu}_{2}\|) \ll \frac{1}{p}\mathbf{z}_{i}^{\mathsf{T}}\mathbf{z}_{j},$$

spectrum-wise:

$$- \|\mathbf{K} - \exp(-1)\mathbf{1}_n\mathbf{1}_n^{\mathsf{T}}\| \neq 0; - \|\frac{1}{p}\mathbf{Z}^{\mathsf{T}}\mathbf{Z}\| = O(1) \text{ and } \|g(\|\boldsymbol{\mu}_1 - \boldsymbol{\mu}_2\|)\frac{1}{p}\mathbf{j}\mathbf{j}^{\mathsf{T}}\| = O(1)!$$

Same phenomenon as the sample covariance example: $[\hat{\mathbf{C}} - \mathbf{C}]_{ij} \rightarrow 0 \Rightarrow ||\hat{\mathbf{C}} - \mathbf{C}|| \rightarrow 0!$

 \Rightarrow With **RMT**, we understand kernel spectral clustering for large dimensional data!

Some more numerical results



Figure: Empirical histogram of LS-SVM soft output versus RMT prediction, n = 2048, p = 784, $\gamma = 1$ with Gaussian kernel, for MINST (left, 7 versus 9) and Fashion-MNIST (right, 8 versus 9) data. Results averaged over 30 runs.

²Zhenyu Liao and Romain Couillet. "A Large Dimensional Analysis of Least Squares Support Vector Machines". In: *IEEE Transactions on Signal Processing* 67.4 (2019), pp. 1065–1074

- sample covariance matrix $\hat{\mathbf{C}}$ have different behavior in the large *n*, *p* regime
- ▶ loss of matrix norm "equivalence" for large matrices $\|\mathbf{A}\|_{\max} \le \|\mathbf{A}\| \le p \|\mathbf{A}\|_{\max}$ for $\mathbf{A} \in \mathbb{R}^{p \times p}$ and $\|\mathbf{A}\|_{\max} \equiv \max_{ij} |\mathbf{A}_{ij}|$
- ▶ in the non-trivial classification regime: loss of relevance of Euclidean distance
- direct consequence in all distance-based ML methods, e.g., kernel spectral clustering
- RMT provides an answer

Characterization of scalar random variables: from moments to tails

Definition (Moments and moment generating function, MGF)

For a scalar random variable *x* defined on some probability space $(\Omega, \mathcal{F}, \mathbb{P})$, we denote

- $\mathbb{E}[x]$ the *expectation* of *x*;
- Var $[x] = \mathbb{E}[(x \mathbb{E}[x])^2]$ the variance of *x*;
- for p > 0, $\mathbb{E}[x^p]$ the p^{th} moment of x, and $\mathbb{E}[|x|^p]$ the p^{th} absolute moment;
- for $\lambda \in \mathbb{R}$, $M_x(\lambda) = \mathbb{E}[e^{\lambda x}] = \sum_{p=0}^{\infty} \frac{\lambda^p}{p!} \mathbb{E}[x^p]$ the moment generating function (MGF) of x.
- the (absolute) moment of x writes as an integral of the tail of x
- characterization of the probability that *x* differs from a deterministic value by more than t > 0.

Lemma (Moments versus tails)

For a scalar random variable x and fixed p > 0, we have • $\mathbb{E}[|x|^p] = \int_0^\infty pt^{p-1}\mathbb{P}(|x| \ge t) dt$ • $\mathbb{P}(|x| \ge t) \le \exp(-\lambda t)M_x(\lambda)$, for t > 0 and MGF $M_x(\lambda)$

Sub-gaussian distribution

Definition (Sub-gaussian and sub-exponential distributions)

For a standard Gaussian random variable $x \sim \mathcal{N}(0, 1)$, its law given by $\mu(dt) = \frac{1}{\sqrt{2\pi}} \exp(-t^2/2)$, so that $\mathbb{P}(x \ge X) = \mu([X, \infty)) = \frac{1}{\sqrt{2\pi}} \int_X^\infty \exp(-t^2/2) dt \le \exp(-X^2/2)$.

We say y is a sub-gaussian random variable if it has a tail that decays as fast as standard Gaussian random variables, that is

$$\mathbb{P}\left(|y| \ge t\right) \le \exp(-t^2/\sigma_{\mathcal{N}}^2),\tag{1}$$

for some $\sigma_N > 0$ (known as the *sub-gaussian norm* of *y*) for all t > 0.

▶ We can define a *sub-exponential random variable z* similarly via $\mathbb{P}(|z| \ge t) \le \exp(-t/\sigma_N)$.

▶ for a sub-gaussian random variable *x* of mean $\mu = \mathbb{E}[x]$ and sub-gaussian norm σ_N that

$$\mathbb{P}\left(|x-\mu| \ge t\sigma_{\mathcal{N}}\right) \le \exp(-t^2),\tag{2}$$

for all t > 0, in which the sub-gaussian norm σ_N of x acts as a scale parameter (that is similar, in spirit, to the variance parameter of Gaussian distribution).

A collection of scalar random variables: from LLN to CLT

For a collection of independent and identically distributed (i.i.d.) random variables x_1, \ldots, x_n of mean μ and variance σ^2 , we have, by independence, that

$$\mathbb{E}\left[\frac{1}{n}\sum_{i=1}^{n}x_{i}\right] = \mu, \quad \operatorname{Var}\left[\frac{1}{n}\sum_{i=1}^{n}x_{i}\right] = \frac{1}{n^{2}}\sum_{i=1}^{n}\operatorname{Var}[x_{i}] = \frac{\sigma^{2}}{n}.$$
(3)

• for μ , σ^2 do *not* scale with *n*, the (random) sample mean strongly concentrates around its expectation μ .

Theorem (Weak and strong law of large numbers, LLN)

For a sequence of i.i.d. random variables x_1, \ldots, x_n *with finite expectation* $\mathbb{E}[x_i] = \mu < \infty$ *, we have*

- ▶ the sample mean $\frac{1}{n}\sum_{i=1}^{n} x_i \rightarrow \mu$ in probability as $n \rightarrow \infty$, known as the weak law of large numbers (WLLN);
- ▶ the sample mean $\frac{1}{n}\sum_{i=1}^{n} x_i \rightarrow \mu$ almost surely as $n \rightarrow \infty$, known as the strong law of large numbers (SLLN).

A collection of scalar random variables: from LLN to CLT

Theorem (Central limit theorem, CLT)

For a sequence of i.i.d. random variables x_1, \ldots, x_n with $\mathbb{E}[x_i] = \mu$ and $\operatorname{Var}[x_i] = \sigma^2$, we have, for every $t \in \mathbb{R}$ that

$$\mathbb{P}\left(\frac{1}{\sigma\sqrt{n}}\sum_{i=1}^{n}(x_{i}-\mu)\geq t\right)\rightarrow\frac{1}{\sqrt{2\pi}}\int_{t}^{\infty}e^{-x^{2}/2}\,dx\tag{4}$$

as $n \to \infty$. That is, as $n \to \infty$, the random variable $\frac{1}{\sigma\sqrt{n}}\sum_{i=1}^{n}(x_i - \mu) \to \mathcal{N}(0, 1)$ in distribution.

Remark: the results of LLN and CLT can be compactly written as

$$\frac{1}{n}\sum_{i=1}^{n} x_{i} \simeq \underbrace{\mu}_{O(1)} + \underbrace{\mathcal{N}(0,1) \cdot \sigma / \sqrt{n}}_{O(n^{-1/2})},$$
(5)

as $n \to \infty$, for μ, σ both of order O(1).

- (i) In the first order (of magnitude O(1)), it has an asymptotically deterministic behavior around the expectation μ ; and
- (ii) in the second order (of magnitude $O(n^{-1/2})$), it strongly concentrates around this deterministic quantity with a universal Gaussian fluctuation, regardless of the distribution of the component of x_i .

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Concentration of random vectors in high dimensions?

• "concentration" for a random vector $\mathbf{x} \in \mathbb{R}^n$?

Observation (Random vectors do not "concentrate" around their means)

For two *independent* random vectors $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$, having i.i.d. entries with zero mean and unit variance (that is, $\mu = 0$ and $\sigma = 1$), we have that

$$\mathbb{E}[\|\mathbf{x} - \mathbf{0}\|_{2}^{2}] = \mathbb{E}[\mathbf{x}^{\mathsf{T}}\mathbf{x}] = \operatorname{tr}(\mathbb{E}[\mathbf{x}\mathbf{x}^{\mathsf{T}}]) = n,$$
(6)

and further by independence that

$$\mathbb{E}[\|\mathbf{x} - \mathbf{y}\|_{2}^{2}] = \mathbb{E}[\mathbf{x}^{\mathsf{T}}\mathbf{x} + \mathbf{y}^{\mathsf{T}}\mathbf{y}] = 2n.$$
(7)

- the origin **0** (and *mean* of **x**) is always, in expectation, at the midpoint of two independent draws of random vectors in \mathbb{R}^n
- any random vector $\mathbf{x} \in \mathbb{R}^n$ with *n* large is not close to its mean
- **x** does not itself "concentrate" around any *n*-dimensional deterministic vector in any traditional sense.

Concentration of random vectors and their linear scalar observations

- ▶ In spite of this, from the LLN and CLT one expects that some types of "observations" of $\mathbf{x} \in \mathbb{R}^n$ (e.g., averages over all the entries of \mathbf{x} , to retrieve the sample mean), must concentrate in some sense for *n* large
- we "interpret" the sample mean as a linear scalar observation of a vector $\mathbf{x} \in \mathbb{R}^n$.

Remark (Sample mean as a linear scalar observation)

Let $\mathbf{x} \in \mathbb{R}^n$ be a random vector having i.i.d. entries, then the sample mean of the entries of \mathbf{x} can be rewritten as the following linear scalar observation $f : \mathbb{R}^n \to \mathbb{R}$ of \mathbf{x} defined as

$$f(\mathbf{x}) = \mathbf{1}_n^{\mathsf{T}} \mathbf{x}/n = \frac{1}{n} \sum_{i=1}^n x_i, \text{ or } f(\cdot) = \mathbf{1}_n^{\mathsf{T}}(\cdot)/n.$$
(8)

- LLN and CLT are nothing but asymptotic characterization of the concentration behavior of the linear scalar observation $f(\mathbf{x})$ of the random vector $\mathbf{x} \in \mathbb{R}^n$
- we can say things non-asymptotically as well, under two different assumptions on the tail of x.
 - (i) are only assumed to have finite variance σ^2 (but nothing on its tail behavior or higher-order moments); and
 - (ii) have sub-gaussian tails with sub-gaussian norm σ_N .

Asymptotic and non-asymptotic concentration of random vectors

Table: Different types of characterizations of the linear scalar observation $f(\mathbf{x}) = \mathbf{x}^{\mathsf{T}} \mathbf{1}_n / n$ for $\mathbf{x} \in \mathbb{R}^n$, having i.i.d. entries with mean $\mathbb{E}[x_i] = \mu$ and variance σ^2 or sub-gaussian norm σ_N .

First-order behavior		Second-order behavior	
Asymptotic	$f(\mathbf{x}) ightarrow \mu$ via Law of Large Numbers	$rac{\sqrt{n}}{\sigma}(f(\mathbf{x})-\mu) ightarrow\mathcal{N}(0,1)$ in law Central Limit Theorem	
Non-asymptotic under finite variance	$\mathbb{E}[f(\mathbf{x})] = \mu$	$\mathbb{P}\left(f(\mathbf{x}) - \mu \ge t\sigma/\sqrt{n}\right) \le t^{-2}$ via variance computation and Chebyshev's inequality	
Non-asymptotic under sub-gaussianity	$\mathbb{E}[f(\mathbf{x})] = \mu$	$\mathbb{P}\left(f(\mathbf{x}) - \mu \ge t\sigma_{\mathcal{N}}/\sqrt{n}\right) \le \exp(-Ct^2)$ via sub-gaussian tail bound	

Remark (Concentration of scalar observation of large random vectors: asymptotic and non-asymptotics): A random vector $\mathbf{x} \in \mathbb{R}^n$, when "observed" via the linear scalar observation $f(\mathbf{x}) = \mathbf{1}_n^{\mathsf{T}} \mathbf{x}/n$:

$$f(\mathbf{x}) \simeq \underbrace{\mu}_{O(1)} + \underbrace{X/\sqrt{n}}_{O(n^{-1/2})},\tag{9}$$

for *n* large, with some random *X* of order O(1) that:

- (i-i) has a tail that decays (at least) as t^{-2} , for finite *n* and **x** having entries of bounded variance;
- (i-ii) has a sub-gaussian tail (at least) as $exp(-t^2)$, for finite *n* and **x** having sub-gaussian entries;
 - (ii) has a precise Gaussian tail *independent* of the law of (the entries of) \mathbf{x} , but in the limit of $n \to \infty$ via CLT.

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Lipschitz, quadratic concentration, and beyond

The concentration properties extend beyond the specific *linear* observation, $f(\mathbf{x}) = \mathbf{1}_n^{\mathsf{T}} \mathbf{x}/n$, to many types of (possibly) nonlinear observations.

Definition (Observation maps)

For random vector $\mathbf{x} \in \mathbb{R}^n$, we say $f(\mathbf{x}) \in \mathbb{R}$ is a scalar observation of \mathbf{x} with observation map $f \colon \mathbb{R}^n \to \mathbb{R}$.

Table: Different types of scalar observations $f(\mathbf{x})$ of random vector $\mathbf{x} \in \mathbb{R}^n$, having independent entries.

	Scalar observation	Characterization
Linear	sample mean $f(\mathbf{x}) = 1_n^{T} \mathbf{x} / n$, and $f(\mathbf{x}) = \mathbf{a}^{T} \mathbf{x}$ for $\mathbf{a} \in \mathbb{R}^n$	Table in last slide
Lipschitz	$f(\mathbf{x})$ for a Lipschitz map $f \colon \mathbb{R}^n \to \mathbb{R}$	Lipschitz concentration
Quadratic form	$f(\mathbf{x}) = \mathbf{x}^T \mathbf{A} \mathbf{x}$ for some $\mathbf{A} \in \mathbb{R}^{n imes n}$	Hanson–Wright inequality
Nonlinear quadratic form	$f(\mathbf{x}) = \sigma(\mathbf{x}^{T}\mathbf{Y})\mathbf{A}\sigma(\mathbf{Y}^{T}\mathbf{x})$ for entry-wise $\sigma \colon \mathbb{R} \to \mathbb{R}, \mathbf{A} \in \mathbb{R}^{n \times n}$ and $\mathbf{Y} \in \mathbb{R}^{p \times n}$	Nonlinear quadratic concentration, of direct use in NN

Lipschitz concentration

Theorem (Concentration of Lipschitz map of Gaussian random vectors, [Ver18, Theorem 5.2.2])

For a standard Gaussian random vector $\mathbf{x} \sim \mathcal{N}(\mathbf{0}, \mathbf{I}_n)$ and a Lipschitz function $f : \mathbb{R}^n \to \mathbb{R}$ that satisfies $|f(\mathbf{y}_1) - f(\mathbf{y}_2)| \leq K_f ||\mathbf{y}_1 - \mathbf{y}_2||_2$ for any $\mathbf{y}_1, \mathbf{y}_2 \in \mathbb{R}^n$, we have, for all t > 0 that

$$\mathbb{P}\left(\left|f(\mathbf{x}) - \mathbb{E}[f(\mathbf{x})]\right| \ge t\right) \le \exp(-Ct^2/K_f^2),\tag{10}$$

for some universal constant C > 0, with $K_f > 0$ known as the Lipschitz constant of f.

Remark (Concentration of Lipschitz observation of large random vectors): The Lipschitz scalar observations $f(\mathbf{x})$ of the random vector $\mathbf{x} \in \mathbb{R}^n$ behave as

$$f(\mathbf{x}) \simeq \mathbb{E}[f(\mathbf{x})] + K_f, \tag{11}$$

for *n* large, where K_f is the Lipschitz constant of *f* (that is, in general, of order $O(n^{-1/2})$, for example for

- $f(\mathbf{x}) = \mathbf{x}^{\mathsf{T}} \mathbf{1}_n / n$). This leads to first- and second-order behaviors:
 - (i) In the first order, $f(\mathbf{x})$ fluctuate around the deterministic quantity $\mathbb{E}[f(\mathbf{x})]$; and
 - (ii) in the second order, it concentrates around this deterministic quantity with a fluctuation/deviation that is proportional to K_f (and or order $O(n^{-1/2})$) and has a sub-gaussian tail

³Roman Vershynin. High-Dimensional Probability: An Introduction with Applications in Data Science. Cambridge Series in Statistical and Probabilistic Mathematics. Cambridge University Press, 2018

Concentration of quadratic forms

intuitively expect that non-Lipschitz observation f(x) still concentrates in some way, but "less so"
 important special case of quadratic forms, x^TAx for some given A ∈ ℝ^{n×n}

Theorem (Hanson–Wright inequality for quadratic forms, [Ver18, Theorem 6.2.1])

For a random vector $\mathbf{x} \in \mathbb{R}^n$ having independent, zero-mean, unit-variance, sub-gaussian entries with sub-gaussian norm bounded by σ_N , and deterministic matrix $\mathbf{A} \in \mathbb{R}^{n \times n}$, we have, for every t > 0, that

$$\mathbb{P}\left(\left|\mathbf{x}^{\mathsf{T}}\mathbf{A}\mathbf{x} - \operatorname{tr}\mathbf{A}\right| \ge t\right) \le \exp\left(-\frac{C}{\sigma_{\mathcal{N}}^{2}}\min\left(\frac{t^{2}}{\sigma_{\mathcal{N}}^{2}\|\mathbf{A}\|_{F}^{2}}, \frac{t}{\|\mathbf{A}\|_{2}}\right)\right),\tag{12}$$

for some universal constant C > 0.

• depending on the interplay between the "range" *t* and the deterministic matrix **A**, the random quadratic form $\mathbf{x}^T \mathbf{A} \mathbf{x}$ swings between a sub-gaussian (exp($-t^2$)) and a sub-exponential (exp(-t)) tail

Remark: squared norm $\|\mathbf{x}\|_2^2$ as quadratic observation of $\mathbf{x} \in \mathbb{R}^n$: $\frac{1}{n} \|\mathbf{x}\|_2^2 \simeq 1 + O(n^{-1/2})$ for *n* large,

- (i) In the first order, $\|\mathbf{x}\|_2^2/n$ fluctuate around the deterministic quantity one; and
- (ii) in the second order, it concentrates around this deterministic quantity with a fluctuation/deviation that grows with σ_N^2 and of order $O(n^{-1/2})$ with a sub-gaussian tail when close to the deterministic quantity, and with a sub-exponential tail (so with a fluctuation with heavier tail and concentrates "less" than the Lipschitz case) when far away.

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Concentration of nonlinear quadratic forms

• nonlinear quadratic forms $\frac{1}{n}f(\mathbf{x}^{\mathsf{T}}\mathbf{Y})\mathbf{A}f(\mathbf{Y}^{\mathsf{T}}\mathbf{x})$ for Gaussian $\mathbf{x} \in \mathbb{R}^{p}$ and deterministic $\mathbf{A} \in \mathbb{R}^{n \times n}$, $\mathbf{Y} \in \mathbb{R}^{p \times n}$

Theorem (Concentration of nonlinear quadratic forms, [LtC18, Lemma 1])

For a standard Gaussian random vector $\mathbf{x} \sim \mathcal{N}(\mathbf{0}, \mathbf{I}_p)$ and deterministic $\mathbf{A} \in \mathbb{R}^{n \times n}$, $\mathbf{Y} \in \mathbb{R}^{p \times n}$ such that $\|\mathbf{A}\|_2 \leq 1$, $\|\mathbf{Y}\|_2 = 1$, we have, for Lipschitz function $f : \mathbb{R} \to \mathbb{R}$ with Lipschitz constant K_f and any t > 0 that

$$\mathbb{P}\left(\left|\frac{1}{n}f(\mathbf{x}^{\mathsf{T}}\mathbf{Y})\mathbf{A}f(\mathbf{Y}^{\mathsf{T}}\mathbf{x}) - \frac{1}{n}\operatorname{tr}\mathbf{A}\mathbf{K}_{f}(\mathbf{Y})\right| \geq \frac{t}{\sqrt{n}}\right) \leq \exp\left(-\frac{C}{K_{f}^{2}}\min\left(\frac{t^{2}}{(|f(0)| + K_{f}\sqrt{p/n})^{2}}, \sqrt{n}t\right)\right), \quad (13)$$

with $\mathbf{K}_{f}(\mathbf{Y}) = \mathbb{E}_{\mathbf{x}}[f(\mathbf{Y}^{\mathsf{T}}\mathbf{x})f(\mathbf{x}^{\mathsf{T}}\mathbf{Y})] \in \mathbb{R}^{n \times n}$, for some universal constant C > 0.

▶ a nonlinear extension of the Hanson–Wright inequality (consider, e.g., $\mathbf{Y} = \mathbf{I}_n$ with p = n) **Remark** (Concentration of nonlinear quadratic form observation of large random vectors):

$$\frac{1}{n}f(\mathbf{x}^{\mathsf{T}}\mathbf{Y})\mathbf{A}f(\mathbf{Y}^{\mathsf{T}}\mathbf{x}) \simeq \frac{1}{n}\operatorname{tr}\mathbf{A}\mathbf{K}_{f}(\mathbf{Y}) + O(n^{-1/2}),\tag{14}$$

for *n* large, with $\max\{f(0), K_f, p/n\} = O(1)$, and similar first and second order behavior as above.

⁴Cosme Louart, Zhenyu Liao, and Romain Couillet. "A random matrix approach to neural networks". In: Annals of Applied Probability 28.2 (2018), pp. 1190–1248

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Lemma (Polarization identity)

For
$$\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$$
, we have $\mathbf{x}^{\mathsf{T}} \mathbf{y} = \frac{1}{2} (\|\mathbf{x}\|_2^2 + \|\mathbf{y}\|_2^2 - \|\mathbf{x} - \mathbf{y}\|_2^2)$.

Observation (Different scaling for inner products and Euclidean norms of large random vectors)

Consider a random vector $\mathbf{x} \in \mathbb{R}^n$, so that $\sqrt{n}\mathbf{x}$ has i.i.d. entries with zero mean, unit variance, and finite fourth order moment $m_4 < \infty$ (the scaling by \sqrt{n} is so that $\mathbb{E}[\|\mathbf{x}\|_2^2] = 1$), and a deterministic vector $\mathbf{y} \in \mathbb{R}^n$ of unit norm $\|\mathbf{y}\|_2 = 1$. Then, by LLN and CLT

$$\mathbf{x}^{\mathsf{T}}\mathbf{y} \simeq 0 + \mathcal{N}(0,1) / \sqrt{n},\tag{15}$$

for *n* large, so inner product $\mathbf{x}^{\mathsf{T}}\mathbf{y} = O(n^{-1/2})$. On the other hand, $\mathbb{E}[(\mathbf{x}^{\mathsf{T}}\mathbf{x})^2] = \frac{n+m_4-1}{n}$ and

$$\|\mathbf{x}\|_{2}^{2} = \mathbf{x}^{\mathsf{T}}\mathbf{x} \simeq 1 + \mathcal{N}(0, m_{4} - 1) / \sqrt{n}, \quad \|\mathbf{x} - \mathbf{y}\|_{2}^{2} = \|\mathbf{x}\|_{2}^{2} + \|\mathbf{y}\|_{2}^{2} + O(n^{-1/2}) = 2 + O(n^{-1/2}), \quad (16)$$

so that the Euclidean distance between **x** and any fixed **y** (or their norms) is much larger (in fact by a factor of \sqrt{n}) than their inner product.

Numerical illustration



Figure: Visualization of the polarization identity or (a) *deterministic* $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ and (b) large-dimensional random vector $\mathbf{x} \in \mathbb{R}^n$ and deterministic $\mathbf{y} \in \mathbb{R}^n$.

A quick recap on linear algebra: matrices

Definition (Matrix inner product and Frobenius norm)

Given matrices $\mathbf{X}, \mathbf{Y} \in \mathbb{R}^{m \times n}$,

- ► tr($\mathbf{X}^{\mathsf{T}}\mathbf{Y}$) = $\sum_{i=1}^{n} [\mathbf{X}^{\mathsf{T}}\mathbf{Y}]_{ii} = \sum_{i=1}^{n} \sum_{j=1}^{m} X_{ji}Y_{ji}$ is the matrix inner product between **X** and **Y**, where tr(**A**) is the trace of **A**; and
- ► $\|\mathbf{X}\|_F^2 = \operatorname{tr}(\mathbf{X}^T \mathbf{X}) = \sum_{i=1}^n [\mathbf{X}^T \mathbf{X}]_{ii} = \sum_{i=1}^n \sum_{j=1}^m X_{ji}^2$ denotes the (squared) Frobenius norm of **X**, which is also the sum of the squared entries of **X**.

Definition (Matrix norm)

For $\mathbf{X} \in \mathbb{R}^{p \times n}$, the following "entry-wise" extension of the *p*-norms of vectors.

• matrix Frobenius norm $\|\mathbf{X}\|_F = \sqrt{\sum_{i,j} X_{ij}^2} = \|\operatorname{vec}(\mathbf{X})\|_2$ that extends the vector ℓ_2 Euclidean norm; and

• matrix maximum norm $\|\mathbf{X}\|_{\max} = \max_{i,j} |X_{ij}| = \|\operatorname{vec}(\mathbf{X})\|_{\infty}$ that extends the vector ℓ_{∞} norm. and also matrix norm induced by vectors: $\|\mathbf{X}\|_p \equiv \sup_{\|\mathbf{v}\|_p=1} \|\mathbf{X}\mathbf{v}\|_p$.

► taking p = 2 is the spectral norm: $\|\mathbf{X}\|_2 = \sqrt{\lambda_{\max}(\mathbf{X}\mathbf{X}^{\mathsf{T}})} = \sigma_{\max}(\mathbf{X})$, with $\lambda_{\max}(\mathbf{X}\mathbf{X}^{\mathsf{T}})$ and $\sigma_{\max}(\mathbf{X})$ the maximum eigenvalue and singular of $\mathbf{X}\mathbf{X}^{\mathsf{T}}$ and \mathbf{X} , respectively.

A quick recap on linear algebra: matrices

- Frobenius norm and spectral norm are matrix Schatten norms (that applies the vector *p*-norms on the vector of singular values of the matrix)
- are known to be unitarily invariant, that is ||X|| = ||UXV|| for all matrices X and unitary matrices U, V of appropriate dimensions

Remark (Matrix norm "equivalence")

For a matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$ *, one has the following*

- $\|\mathbf{A}\|_2 \le \|\mathbf{A}\|_F \le \sqrt{\operatorname{rank}(\mathbf{A})} \cdot \|\mathbf{A}\|_2 \le \sqrt{\max(m,n)} \cdot \|\mathbf{A}\|_2$, so that the control of the spectral norm via the Frobenius norm can be particularly loose for matrices of large rank; and
- $\|\mathbf{A}\|_{\max} \le \|\mathbf{A}\|_2 \le \sqrt{mn} \cdot \|\mathbf{A}\|_{\max}$, with $\|\mathbf{A}\|_{\max} \equiv \max_{i,j} |A_{ij}|$ the max norm of \mathbf{A} , so that the max and spectral norm can be significantly different for matrices of large size.
- The fact that matrix norm "equivalence" holds only up to dimensional factors (e.g., rank and size) is crucial in large-dimensional data analysis and ML, as we have seen in the examples of SCM and kernel spectral clustering above.

A quick recap on linear algebra: eigenspectral decomposition

Definition (Eigen-decomposition of symmetric matrices)

A symmetric real matrix $\mathbf{X} \in \mathbb{R}^{n \times n}$ admits the following eigen-decomposition

$$\mathbf{X} = \mathbf{U}_{\mathbf{X}} \mathbf{\Lambda}_{\mathbf{X}} \mathbf{U}_{\mathbf{X}}^{\mathsf{T}} = \sum_{i=1}^{n} \lambda_i(\mathbf{X}) \mathbf{u}_i \mathbf{u}_i^{\mathsf{T}},$$
(17)

for diagonal $\Lambda_{\mathbf{X}} = \text{diag}\{\lambda_i(\mathbf{X})\}_{i=1}^n$ containing $\lambda_1(\mathbf{X}), \dots, \lambda_n(\mathbf{X})$ the real eigenvalues of \mathbf{X} , and orthonormal $\mathbf{U}_{\mathbf{X}} = [\mathbf{u}_1, \dots, \mathbf{u}_n] \in \mathbb{R}^{n \times n}$ containing the corresponding eigenvectors. In particular,

$$\mathbf{X}\mathbf{u}_i = \lambda_i(\mathbf{X})\mathbf{u}_i. \tag{18}$$

- ► interested in a single eigenvalue of a symmetric real matrix, $\mathbf{X} \in \mathbb{R}^{n \times n}$, one may either resort to the eigenvalue-eigenvector equation in (18) or the determinant equation $\det(\mathbf{X} \lambda \mathbf{I}_n) = 0$
- classical RMT is interested in the *joint* behavior of all eigenvalues $\lambda_1(\mathbf{X}), \ldots, \lambda_n(\mathbf{X})$, e.g., the (empirical) eigenvalue distribution of **X**

Definition (Empirical Spectral Distribution, ESD)

For a real symmetric matrix $\mathbf{X} \in \mathbb{R}^{n \times n}$, the *empirical spectral distribution* (ESD) or *empirical spectral measure* $\mu_{\mathbf{X}}$ of **X** is defined as the normalized counting measure of the eigenvalues $\lambda_1(\mathbf{X}), \ldots, \lambda_n(\mathbf{X})$ of **X**,

$$\mu_{\mathbf{X}} \equiv \frac{1}{n} \sum_{i=1}^{n} \delta_{\lambda_i(\mathbf{X})},\tag{19}$$

where δ_x represents the Dirac measure at x. Since $\int \mu_{\mathbf{X}}(dx) = 1$, the spectral measure $\mu_{\mathbf{X}}$ of a matrix $\mathbf{X} \in \mathbb{R}^{n \times n}$ (which may be random or not) is a probability measure.

∫ tµ_X(dt) = 1/n Σ_{i=1}ⁿ λ_i(X) is the first moment of µ_X, and gives the average of all eigenvalues of X; and
 ∫ t²µ_X(dt) = 1/n Σ_{i=1}ⁿ λ_i²(X) is the second moment of µ_X, so that ∫ t²µ_X(dt) - (∫ tµ_X(dt))² gives the variance of the eigenvalues of X.

Connection between linear equation and spectral decomposition

Consider the linear equation

$$\mathbf{A}\mathbf{x} = \mathbf{b},\tag{20}$$

with $\mathbf{A} \in \mathbb{R}^{p \times n}$ and $\mathbf{b} \in \mathbb{R}^{p}$, we aim to solve for $\mathbf{x} \in \mathbb{R}^{n}$ solution to Equation (20).

For square **A** with p = n, then Equation (20) admits a unique solution if and only if **A** is invertible, that is, 0 is not an eigenvalue of **A**, and the solution is given by

$$\mathbf{x} = \mathbf{A}^{-1}\mathbf{b}.\tag{21}$$

▶ in the general case with $p \neq n$, **A** can be a fat (p < n) or tail (p > n) matrix, and is not invertible in either case, we use the Moore–Penrose pseudoinverse.

Definition (Moore–Penrose pseudoinverse)

For a real matrix $\mathbf{X} \in \mathbb{R}^{p \times n}$, we say $\mathbf{X}^+ \in \mathbb{R}^{n \times p}$ is a (Moore–Penrose) pseudoinverse of \mathbf{X} if it satisfies $\mathbf{X}\mathbf{X}^+\mathbf{X} = \mathbf{X}$, $\mathbf{X}^+\mathbf{X}\mathbf{X}^+ = \mathbf{X}^+$, and both $\mathbf{X}\mathbf{X}^+$ and $\mathbf{X}^+\mathbf{X}$ are symmetric. In particular, for $\mathbf{X} = \mathbf{U}_{\mathbf{X}}\mathbf{\Sigma}_{\mathbf{X}}\mathbf{V}_{\mathbf{X}}^{\mathsf{T}}$ the SVD of \mathbf{X} , with orthonormal $\mathbf{U}_{\mathbf{X}} \in \mathbb{R}^{p \times p}$ and $\mathbf{V}_{\mathbf{X}} \in \mathbb{R}^{n \times n}$, the pseudoinverse of \mathbf{X} can be written as

$$\mathbf{X}^{+} = \mathbf{V}_{\mathbf{X}} \boldsymbol{\Sigma}_{\mathbf{X}}^{-1} \mathbf{U}_{\mathbf{X}}, \tag{22}$$

with Σ_{χ}^{-1} inverting all positive values in Σ_{χ} and leaving zeros unchanged.

Regularized inverse

The pseudoinverse "solves" the linear equation Ax = b in the following sense:

The solutions to Equation (20) exist if and only if $AA^+b = b$, and all its solutions are given by

$$\mathbf{x} = \mathbf{A}^{+}\mathbf{b} + (\mathbf{I}_{n} - \mathbf{A}^{+}\mathbf{A})\mathbf{y},$$
(23)

for arbitrary $\mathbf{y} \in \mathbb{R}^n$. The solution is unique if and only if $\mathbf{I}_n - \mathbf{A}^+ \mathbf{A} = \mathbf{0}$ and that \mathbf{A} has full column rank. As a consequence, the solution $\hat{\mathbf{x}} = \mathbf{A}^+ \mathbf{b}$ provides the least squares solution to Equation (20), as

$$\underset{\mathbf{x}\in\mathbb{R}^{n}}{\arg\min}\|\mathbf{A}\mathbf{x}-\mathbf{b}\|_{2}=\mathbf{A}^{+}\mathbf{b}. \tag{24}$$

- however, can be numerically unstable as it inverts all singular values $\sigma(\mathbf{X})$ of \mathbf{X} to $1/\sigma(\mathbf{X})$, see later (e.g., Part 3) for a manifestation of this under the (modern) name of double descent
- ▶ in the case of square **X**, an alternative is the regularized inverse of **X**,

$$\mathbf{Q}_{\mathbf{X}}(\gamma) = (\mathbf{X} + \gamma \mathbf{I})^{-1}, \tag{25}$$

for some regularization parameter $\gamma > 0$, with $\lambda_i(\mathbf{Q}_{\mathbf{X}}(\gamma)) = \frac{1}{\lambda_i(\mathbf{X}) + \gamma}$, and $\|\mathbf{Q}_{\mathbf{X}}\| \le 1/\gamma$.

▶ solves the regularized linear equation (i.e., ridge regression) as

$$\underset{\mathbf{x}\in\mathbb{R}^{n}}{\arg\min}\|\mathbf{A}\mathbf{x}-\mathbf{b}\|_{2}+\gamma\|\mathbf{x}\|_{2}=\mathbf{A}^{\mathsf{T}}(\mathbf{A}\mathbf{A}^{\mathsf{T}}+\gamma\mathbf{I}_{p})^{-1}\mathbf{b}=(\mathbf{A}^{\mathsf{T}}\mathbf{A}+\gamma\mathbf{I}_{n})^{-1}\mathbf{A}^{\mathsf{T}}\mathbf{b}.$$
(26)

• two solutions equivalent for any $\gamma > 0$, taking $\gamma \to 0$ is the "ridgeless" least squares solution $\mathbf{A}^+ \mathbf{b}$.

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A unified spectral analysis approach via the resolvent

- ▶ Note: here everything hold deterministically, not necessarily random yet
- combined with **deterministic equivalent** technique to be discussed in Part 2, gives the whole picture

Definition (Resolvent)

For a symmetric matrix $\mathbf{X} \in \mathbb{R}^{p \times p}$, the resolvent $\mathbf{Q}_{\mathbf{X}}(z)$ of \mathbf{X} is defined, for $z \in \mathbb{C}$ not an eigenvalue of \mathbf{X} , as

$$\mathbf{Q}_{\mathbf{X}}(z) \equiv \left(\mathbf{X} - z\mathbf{I}_{p}\right)^{-1}.$$
(27)

Proposition (Properties of resolvent)

For $\mathbf{Q}_{\mathbf{X}}(z)$ the resolvent of a symmetric matrix $\mathbf{X} \in \mathbb{R}^{p \times p}$ with ESD $\mu_{\mathbf{X}}$ with supported on supp $(\mu_{\mathbf{X}})$, then

- (i) $\mathbf{Q}_{\mathbf{X}}(z)$ is complex analytic on its domain of definition $\mathbb{C} \setminus \operatorname{supp}(\mu_{\mathbf{X}})$;
- (ii) it is bounded in the sense that $\|\mathbf{Q}_{\mathbf{X}}(z)\|_2 \leq 1/\operatorname{dist}(z, \operatorname{supp}(\mu_{\mathbf{X}}));$
- (iii) $x \mapsto \mathbf{Q}_{\mathbf{X}}(x)$ for $x \in \mathbb{R} \setminus \operatorname{supp}(\mu_{\mathbf{X}})$ is an increasing matrix-valued function with respect to symmetric matrix partial ordering (i.e., $\mathbf{A} \succeq \mathbf{B}$ whenever $\mathbf{z}^{\mathsf{T}}(\mathbf{A} \mathbf{B})\mathbf{z} \ge 0$ for all \mathbf{z}).

A unified spectral analysis approach via the resolvent

- for real *z*, the resolvent $Q_X(z)$ is nothing but a regularized inverse of X
- ▶ when interested in the eigenvalues and eigenvectors of $X \in \mathbb{R}^{p \times p}$, consider the eigenvalue and eigenvector equation

$$\mathbf{X}\mathbf{v} = \lambda \mathbf{v} \Leftrightarrow (\mathbf{X} - \lambda \mathbf{I}_p)\mathbf{v} = \mathbf{0}, \quad \lambda \in \mathbb{R}, \mathbf{v} \in \mathbb{R}^p,$$
(28)

for an eigenvalue-eigenvector pair (λ, \mathbf{v}) of **X** with $\mathbf{v} \neq \mathbf{0}$

- again a linear system, but solving for a pair of eigenvalue and eigenvector (λ, v) for which the inverse/resolvent (X − λI_p)⁻¹ does not exist
- while seemingly less convenient at first sight, turns out to be very efficient in providing a unified assess to general spectral functionals of X, by taking z to be complex and exploiting tools from complex analysis

Theorem (Cauchy's integral formula)

For $\Gamma \subset \mathbb{C}$ a positively (i.e., counterclockwise) oriented simple closed curve and a complex function f(z) analytic in a region containing Γ and its inside, then

(i) if
$$z_0 \in \mathbb{C}$$
 is enclosed by $\Gamma, f(z_0) = -\frac{1}{2\pi i} \oint_{\Gamma} \frac{f(z)}{z_0 - z} dz$;

(ii) if not,
$$\frac{1}{2\pi i} \oint_{\Gamma} \frac{f(z)}{z_0 - z} dz = 0.$$

A resolvent approach to spectral analysis

$$(\mathbf{X} - \lambda \mathbf{I}_p)\mathbf{v} = \mathbf{0} \Rightarrow \mathbf{Q}_{\mathbf{X}}(z) = (\mathbf{X} - z\mathbf{I}_n)^{-1}$$
(29)

► let $\mathbf{X} = \mathbf{U} \mathbf{\Lambda} \mathbf{U}^{\mathsf{T}}$ be the spectral decomposition of \mathbf{X} , with $\mathbf{\Lambda} = \{\lambda_i(\mathbf{X})\}_{i=1}^p$ eigenvalues and $\mathbf{U} = [\mathbf{u}_1, \dots, \mathbf{u}_p] \in \mathbb{R}^{p \times p}$ the associated eigenvectors, then

$$\mathbf{Q}(z) = \mathbf{U}(\mathbf{\Lambda} - z\mathbf{I}_p)^{-1}\mathbf{U}^{\mathsf{T}} = \sum_{i=1}^p \frac{\mathbf{u}_i \mathbf{u}_i^{\mathsf{T}}}{\lambda_i(\mathbf{X}) - z}.$$
(30)

thus, same eigenspace as **X**, but maps the eigenvalues $\lambda_i(\mathbf{X})$ of **X** to $1/(\lambda_i(\mathbf{X}) - z)$.

Applying Cauchy's integral formula to the resolvent matrix $Q_X(z)$ allows one to (somewhat magically!) assess the **eigenvalue** and **eigenvector** behavior of **X**:

- characterize the eigenvalues of **X**, one needs to determine a $z \in \mathbb{R}$ such that $\mathbf{Q}_{\mathbf{X}}(z)$ does *not* exist.
- ► can be done by directly calling the Cauchy's integral formula, which allows to determine the value of a (sufficiently nice) function *f* at a point of interest $z_0 \in \mathbb{R}$, by integrating its "inverse" $g_f(z) = f(z)/(z_0 z)$ on the complex plane.
- this "inverse" $g_f(z)$ is akin to the resolvent and does not, by design, exist at the point of interest z_0 .
- ▶ in the following example, we compare the two approaches of
- (i) directly solving the determinantal equation; and
- (ii) use resolvent + Cauchy's integral formula.

A resolvent approach to spectral analysis: an example

Consider the following two-by-two real symmetric random matrix

$$\mathbf{X} = \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \in \mathbb{R}^{2 \times 2},\tag{31}$$

for (say independent) random variables x_1, x_2, x_3 . For $\lambda_1(\mathbf{X})$ and $\lambda_2(\mathbf{X})$ the two (random) eigenvalues of \mathbf{X} with associated (random) eigenvectors $\mathbf{u}_1(\mathbf{X}), \mathbf{u}_2(\mathbf{X}) \in \mathbb{R}^2$, we are interested in

$$f_{\mathbf{X}} = \mathbb{E}\left[f(\lambda_1(\mathbf{X})) + f(\lambda_2(\mathbf{X}))\right], \qquad g_{i,\mathbf{X}} = \mathbf{a}^{\mathsf{T}} \mathbb{E}[\mathbf{u}_i(\mathbf{X})\mathbf{u}_i(\mathbf{X})^{\mathsf{T}}]\mathbf{b}, \ i \in \{1, 2\},$$
(32)

for some function $f \colon \mathbb{R} \to \mathbb{R}$ and deterministic **a**, **b** $\in \mathbb{R}^2$.

(i) Directly solve for the eigenvalues from the determinantal equation as

$$0 = \det(\mathbf{X} - \lambda \mathbf{I}_2) \Leftrightarrow \lambda(\mathbf{X}) = \frac{1}{2} \left(x_1 + x_3 \pm \sqrt{(x_1 + x_3)^2 - 4(x_1 x_3 - x_2^2)} \right),$$
 (33)

and the associated eigenvectors from $\mathbf{X}\mathbf{u}_i(\mathbf{X}) = \lambda_i(\mathbf{X})\mathbf{u}_i(\mathbf{X}), i \in \{1, 2\}$. Then compute $f_{\mathbf{X}} = \mathbb{E}[f(\lambda_1(\mathbf{X})) + f(\lambda_2(\mathbf{X}))], g_{i,\mathbf{X}} = \mathbf{a}^{\mathsf{T}}\mathbb{E}[\mathbf{u}_i(\mathbf{X})\mathbf{u}_i(\mathbf{X})^{\mathsf{T}}]\mathbf{b}$

• needs to **re-compute** of the expectation for a different choice of function *f* and the eigen-pair $(\lambda_1(\mathbf{X}), \mathbf{u}_1(\mathbf{X}))$ or $(\lambda_2(\mathbf{X}), \mathbf{u}_2(\mathbf{X}))$ of interest.

(ii) The **resolvent** approach:

$$\begin{split} f_{\mathbf{X}} &= \mathbb{E}\left[f(\lambda_{1}(\mathbf{X})) + f(\lambda_{2}(\mathbf{X}))\right] \\ &= \mathbb{E}\left[-\frac{1}{2\pi \iota}\oint_{\Gamma}\left(\frac{f(z)}{\lambda_{1}(\mathbf{X}) - z} + \frac{f(z)}{\lambda_{2}(\mathbf{X}) - z}\right)dz\right] \\ &= -\frac{1}{2\pi \iota}\oint_{\Gamma}\mathbb{E}\left[f(z)\operatorname{tr}\mathbf{Q}_{\mathbf{X}}(z)dz\right] = -\frac{1}{2\pi \iota}\oint_{\Gamma}f(z)\operatorname{tr}\left(\mathbb{E}[\mathbf{Q}_{\mathbf{X}}(z)]\right)dz, \end{split}$$

for Γ a positively-oriented contour that circles around both (random) eigenvalues of **X**.

- a much more **unified approach** to the quantity f_X for different choices of f
- compute the expected resolvent once (which is much simpler in the case of large random matrices)
- then perform contour integration with the function f of interest.
- similarly, for $g_{i,\mathbf{X}}$, it follows that

$$g_{i,\mathbf{X}} = \mathbf{a}^{\mathsf{T}} \mathbb{E}[\mathbf{u}_{i}(\mathbf{X})\mathbf{u}_{i}(\mathbf{X})^{\mathsf{T}}]\mathbf{b} = -\frac{1}{2\pi \iota} \oint_{\Gamma_{i}} \mathbf{a}^{\mathsf{T}} \mathbb{E}[\mathbf{Q}_{\mathbf{X}}(z)]\mathbf{b} \, dz$$
(34)

for some contour Γ_i that circles around only $\lambda_i(\mathbf{X}), i \in \{1, 2\}$

Solution given the expected resolvent $\mathbb{E}[\mathbf{Q}(z)]$, it suffices to choose the specific contour Γ_i to get the different expressions of $g_{1,\mathbf{X}}$ and $g_{2,\mathbf{X}}$

Objects of interest	Functionals of resolvent $\mathbf{Q}_{\mathbf{X}}(z)$
ESD $\mu_{\mathbf{X}}$ of \mathbf{X}	Stieltjes transform $m_{\mu_{\mathbf{X}}}(z) = rac{1}{p} \operatorname{tr} \mathbf{Q}_{\mathbf{X}}(z)$
Linear spectral statistics (LSS): $f(\mathbf{X}) \equiv \frac{1}{p} \sum_{i} f(\lambda_{i}(\mathbf{X}))$	Integration of trace of $\mathbf{Q}_{\mathbf{X}}(z)$: $-\frac{1}{2\pi i} \oint_{\Gamma} f(z) \frac{1}{p} \operatorname{tr} \mathbf{Q}_{\mathbf{X}}(z) dz$ (via Cauchy's integral)
Projections of eigenvectors $\mathbf{v}^{T}\mathbf{u}(\mathbf{X})$ and $\mathbf{v}^{T}\mathbf{U}(\mathbf{X})$ onto some given vector $\mathbf{v} \in \mathbb{R}^{p}$	Bilinear form $\mathbf{v}^{T}\mathbf{Q}_{\mathbf{X}}(z)\mathbf{v}$ of $\mathbf{Q}_{\mathbf{X}}$
General matrix functional $F(\mathbf{X}) = \sum_{i} f(\lambda_{i}(\mathbf{X})) \mathbf{v}_{1}^{T} \mathbf{u}_{i}(\mathbf{X}) \mathbf{u}_{i}(\mathbf{X})^{T} \mathbf{v}_{2}$ involving both eigenvalues and eigenvectors	Integration of bilinear form of $\mathbf{Q}_{\mathbf{X}}(z)$: $-\frac{1}{2\pi i} \oint_{\Gamma} f(z) \mathbf{v}_{1}^{T} \mathbf{Q}_{\mathbf{X}}(z) \mathbf{v}_{2} dz$

Using the resolvent to access eigenvalue distribution

Definition (Resolvent)

For a symmetric matrix $\mathbf{X} \in \mathbb{R}^{p \times p}$, the resolvent $\mathbf{Q}_{\mathbf{X}}(z)$ of \mathbf{X} is defined, for $z \in \mathbb{C}$ not an eigenvalue of \mathbf{X} , as

$$\mathbf{Q}_{\mathbf{X}}(z) \equiv \left(\mathbf{X} - z\mathbf{I}_{p}\right)^{-1}.$$
(35)

► let $\mathbf{X} = \mathbf{U} \mathbf{\Lambda} \mathbf{U}^{\mathsf{T}}$ be the spectral decomposition of \mathbf{X} , with $\mathbf{\Lambda} = \{\lambda_i(\mathbf{X})\}_{i=1}^p$ eigenvalues and $\mathbf{U} = [\mathbf{u}_1, \dots, \mathbf{u}_p] \in \mathbb{R}^{p \times p}$ the associated eigenvectors, then

$$\mathbf{Q}(z) = \mathbf{U}(\mathbf{\Lambda} - z\mathbf{I}_p)^{-1}\mathbf{U}^{\mathsf{T}} = \sum_{i=1}^p \frac{\mathbf{u}_i \mathbf{u}_i^{\mathsf{T}}}{\lambda_i(\mathbf{X}) - z}.$$
(36)

- ► thus, same eigenspace as **X**, but maps the eigenvalues $\lambda_i(\mathbf{X})$ of **X** to $1/(\lambda_i(\mathbf{X}) z)$.
- eigenvalue of Q_X(z), and the resolvent matrix itself, must explode as z approaches any eigenvalue of X.
 take the trace tr Q_X(z) of Q_X(z) as the quantity to "locate" the eigenvalues of the matrix X of interest
 for μ_X ≡ ¹/_p Σ^p_{i=1} δ_{λi(X)} the ESD of X,

$$\frac{1}{p}\operatorname{tr} \mathbf{Q}(z) = \frac{1}{p} \sum_{i=1}^{p} \frac{1}{\lambda_i(\mathbf{X}) - z} = \int \frac{\mu_{\mathbf{X}}(dt)}{t - z} \equiv m_{\mu_{\mathbf{X}}}(z)$$
(37)

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The Stieltjes transform

Definition (Stieltjes transform)

For a real probability measure μ with support supp(μ), the *Stieltjes transform* $m_{\mu}(z)$ is defined, for all $z \in \mathbb{C} \setminus \text{supp}(\mu)$, as

$$m_{\mu}(z) \equiv \int \frac{\mu(dt)}{t-z}.$$
(38)

Proposition (Properties of Stieltjes transform, [HLN07])

For m_{μ} the Stieltjes transform of a probability measure μ , it holds that

- (i) m_{μ} is complex analytic on its domain of definition $\mathbb{C} \setminus \text{supp}(\mu)$;
- (ii) it is bounded $|m_{\mu}(z)| \leq 1/\operatorname{dist}(z, \operatorname{supp}(\mu));$
- (iii) it is an increasing function on all connected components of its restriction to $\mathbb{R} \setminus \text{supp}(\mu)$ (since $m'_{\mu}(x) = \int (t-x)^{-2} \mu(dt) > 0$) with $\lim_{x \to \pm \infty} m_{\mu}(x) = 0$ if $\text{supp}(\mu)$ is bounded; and

(iv) $m_{\mu}(z) > 0$ for $z < \inf \operatorname{supp}(\mu)$, $m_{\mu}(z) < 0$ for $z > \sup \operatorname{supp}(\mu)$ and $\Im[z] \cdot \Im[m_{\mu}(z)] > 0$ if $z \in \mathbb{C} \setminus \mathbb{R}$; and

BTW, for any $\mathbf{u} \in \mathbb{R}^p$ and matrix $\mathbf{A} \in \mathbb{R}^{p \times p}$ so that $\operatorname{tr}(\mathbf{A}) = 1$, $\mathbf{u}^{\mathsf{T}} \mathbf{Q}_{\mathbf{X}}(z) \mathbf{u}$, $\operatorname{tr}(\mathbf{A} \mathbf{Q}_{\mathbf{X}}(z))$ are STs.

⁵Walid Hachem, Philippe Loubaton, and Jamal Najim. "Deterministic equivalents for certain functionals of large random matrices". In: *The Annals of Applied Probability* 17.3 (2007), pp. 875–930

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Definition (Inverse Stieltjes transform)

For *a*, *b* continuity points of the probability measure μ , we have

$$\mu([a,b]) = \frac{1}{\pi} \lim_{y \downarrow 0} \int_a^b \Im\left[m_\mu(x+\imath y)\right] \, dx. \tag{39}$$

Besides, if μ admits a density f at x (i.e., $\mu(x)$ is differentiable in a neighborhood of x and $\lim_{\epsilon \to 0} (2\epsilon)^{-1} \mu([x - \epsilon, x + \epsilon]) = f(x))$,

$$f(x) = \frac{1}{\pi} \lim_{y \downarrow 0} \Im \left[m_{\mu}(x + \imath y) \right].$$

$$\tag{40}$$

Use the resolvent for eigenvalue functionals

Definition (Linear Spectral Statistic, LSS)

For a symmetric matrix $\mathbf{X} \in \mathbb{R}^{p \times p}$, the *linear spectral statistics* (LSS) $f_{\mathbf{X}}$ of \mathbf{X} is defined as the averaged statistics of the eigenvalues $\lambda_1(\mathbf{X}), \ldots, \lambda_p(\mathbf{X})$ of \mathbf{X} via some function $f : \mathbb{R} \to \mathbb{R}$, that is

$$f(\mathbf{X}) = \frac{1}{p} \sum_{i=1}^{p} f(\lambda_i(\mathbf{X})).$$
(41)

In particular, we have $= \int f(t)\mu_{\mathbf{X}}(dt)$, for $\mu_{\mathbf{X}}$ the ESD of **X**.

LSS via contour integration: For $\lambda_1(\mathbf{X}), \ldots, \lambda_p(\mathbf{X})$ eigenvalues of a symmetric matrix $\mathbf{X} \in \mathbb{R}^{p \times p}$, some function $f : \mathbb{R} \to \mathbb{R}$ that is complex analytic in a compact neighborhood of the support supp $(\mu_{\mathbf{X}})$ (of the ESD $\mu_{\mathbf{X}}$ of \mathbf{X}), then

$$f(\mathbf{X}) = \int f(t)\mu_{\mathbf{X}}(dt) = -\int \frac{1}{2\pi\iota} \oint_{\Gamma} \frac{f(z)\,dz}{t-z} \mu_{\mathbf{X}}(dt) = -\frac{1}{2\pi\iota} \oint_{\Gamma} f(z)m_{\mu_{\mathbf{X}}}(z)\,dz,\tag{42}$$

for *any* contour Γ that encloses supp $(\mu_{\mathbf{X}})$, i.e., all the eigenvalues $\lambda_i(\mathbf{X})$.

LSS to retrieve the inverse Stieltjes transform formula

Remark (LSS to retrieve the inverse Stieltjes transform formula):

$$\begin{split} &\frac{1}{p}\sum_{\lambda_{i}(\mathbf{X})\in[a,b]}\delta_{\lambda_{i}(\mathbf{X})} = -\frac{1}{2\pi\iota}\oint_{\Gamma}\mathbf{1}_{\Re[z]\in[a-\varepsilon,b+\varepsilon]}(z)m_{\mu_{\mathbf{X}}}(z)\,dz\\ &= -\frac{1}{2\pi\iota}\int_{a-\varepsilon_{\mathbf{X}}-\iota\varepsilon_{\mathbf{Y}}}^{b+\varepsilon_{\mathbf{X}}-\iota\varepsilon_{\mathbf{Y}}}\mathbf{1}_{\Re[z]\in[a-\varepsilon,b+\varepsilon]}(z)m_{\mu_{\mathbf{X}}}(z)\,dz - \frac{1}{2\pi\iota}\int_{b+\varepsilon_{\mathbf{X}}+\iota\varepsilon_{\mathbf{Y}}}^{a-\varepsilon_{\mathbf{X}}+\iota\varepsilon_{\mathbf{Y}}}\mathbf{1}_{\Re[z]\in[a-\varepsilon,b+\varepsilon]}(z)m_{\mu_{\mathbf{X}}}(z)\,dz\\ &- \frac{1}{2\pi\iota}\int_{a-\varepsilon_{\mathbf{X}}+\iota\varepsilon_{\mathbf{Y}}}^{a-\varepsilon_{\mathbf{X}}-\iota\varepsilon_{\mathbf{Y}}}\mathbf{1}_{\Re[z]\in[a-\varepsilon,b+\varepsilon]}(z)m_{\mu_{\mathbf{X}}}(z)\,dz - \frac{1}{2\pi\iota}\int_{b+\varepsilon_{\mathbf{X}}-\iota\varepsilon_{\mathbf{Y}}}^{b+\varepsilon_{\mathbf{X}}+\iota\varepsilon_{\mathbf{Y}}}\mathbf{1}_{\Re[z]\in[a-\varepsilon,b+\varepsilon]}(z)m_{\mu_{\mathbf{X}}}(z)\,dz. \end{split}$$



Figure: Illustration of a rectangular contour Γ and support of μ_X on the complex plane.

Spectral functionals via resolvent

Definition (Matrix spectral functionals)

For a symmetric matrix $\mathbf{X} \in \mathbb{R}^{p \times p}$, we say $F \colon \mathbb{R}^{p \times p} \to \mathbb{R}^{p \times p}$ is a matrix spectral functional of \mathbf{X} ,

$$F(\mathbf{X}) = \sum_{i \in \mathcal{I} \subseteq \{1, \dots, p\}} f(\lambda_i(\mathbf{X})) \mathbf{u}_i \mathbf{u}_i^{\mathsf{T}}, \quad \mathbf{X} = \sum_{i=1}^p \lambda_i(\mathbf{X}) \mathbf{u}_i \mathbf{u}_i^{\mathsf{T}}.$$
 (43)

Spectral functional via contour integration: For $\mathbf{X} \in \mathbb{R}^{p \times p}$, resolvent $\mathbf{Q}_{\mathbf{X}}(z) = (\mathbf{X} - z\mathbf{I}_p)^{-1}$, $z \in \mathbb{C}$, and $f : \mathbb{R} \to \mathbb{R}$ analytic in a neighborhood of the contour $\Gamma_{\mathcal{I}}$ that circles around the eigenvalues $\lambda_i(\mathbf{X})$ of \mathbf{X} with their indices in the set $\mathcal{I} \subseteq \{1, \dots, p\}$,

$$F(\mathbf{X}) = -\frac{1}{2\pi\iota} \oint_{\Gamma_{\mathcal{I}}} f(z) \mathbf{Q}_{\mathbf{X}}(z) \, dz.$$
(44)

Example: access to the *i*-th eigenvector **u**_{*i*} of **X** through

$$\mathbf{u}_{i}\mathbf{u}_{i}^{\mathsf{T}} = -\frac{1}{2\pi\iota} \oint_{\Gamma_{\lambda_{i}(\mathbf{X})}} \mathbf{Q}_{\mathbf{X}}(z) \, dz, \tag{45}$$

for $\Gamma_{\lambda_i(\mathbf{X})}$ a contour circling around $\lambda_i(\mathbf{X})$ only, so eigenvector projection $(\mathbf{v}^{\mathsf{T}}\mathbf{u}_i)^2 = -\frac{1}{2\pi\iota}\oint_{\Gamma_{\lambda_i(\mathbf{X})}} \mathbf{v}^{\mathsf{T}}\mathbf{Q}_{\mathbf{X}}(z)\mathbf{v}\,dz.$

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Take-away messages of this section

- "basic" probability: concentration of scalar observations of large random vectors: simple and involved, linear and nonlinear objects
- boils down to expectation computation/evaluation
- **same** holds for scalar observations of large random matrices
- ▶ linear algebra: matrix norm "equivalence" but up to **dimensional factors**
- resolvent (i.e., regularized inverse) naturally appears in eigenvalue/eigenvector assessment
- a unified resolvent-based to eigenspectral analysis of (not necessarily random) matrices: Cauchy's integral formula, Stieltjes transform (and its inverse), Linear Spectral Statistic, and generic matrix spectral functionals, etc.

Thank you! Q & A?